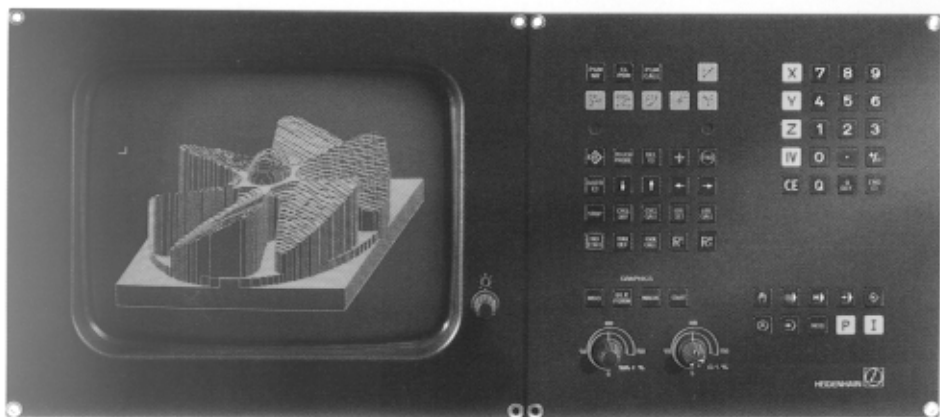


PILOT

TNC 360



HEIDENHAIN

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Comprehensive information on programming possibilities can be found in the Operating Manual.

HEIDENHAIN is constantly working on further developments of its TNC controls. It is therefore possible that details of certain control versions may deviate from the versions explained in this programming PILOT.



Key to Symbols

**Dialog
initiation key**

**Program block
on screen**

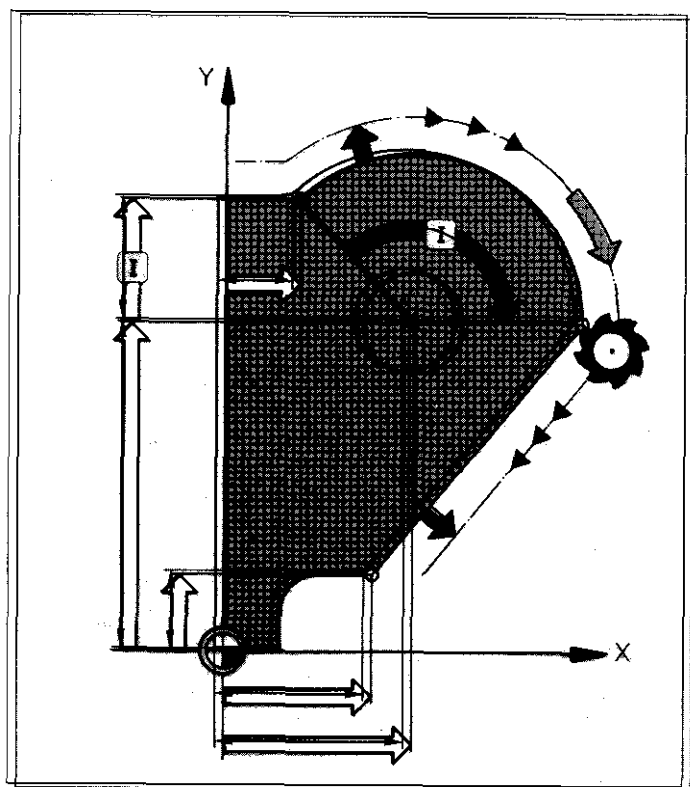
```

11 L X+20 Y+10
    RL F180 M13
  
```

Notes

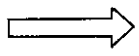
Tool position in the illustrations: Prior to program block execution, the tool is at the start position.

The color designation has the following meaning unless otherwise stated in the specific diagrams (e.g. explanation of cycles).

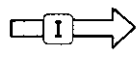


Dimensions

Absolute



Incremental



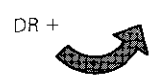
Positive angle
(counter-clockwise)



Negative angle
(clockwise)



Positive rotation



Negative rotation



Tool path

Straight



Circular



Radius compensation


RL/RR



Path Compensation

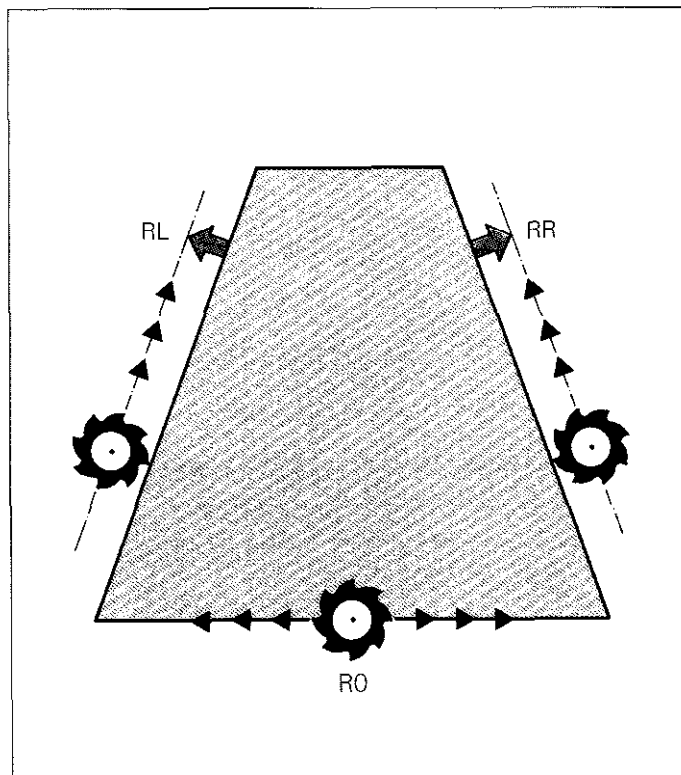
Radius compensation

Tool in milling direction

to the **left** of contour: RL 

to the **right** of contour: RR 

on the contour: RO 

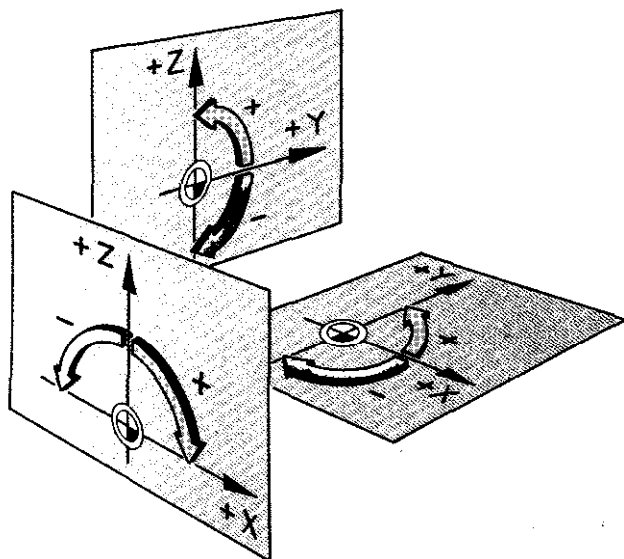


Reference Axes

Working planes

The polar coordinates angle PA and rotation angle ROT are referenced to the reference axis:

Working plane	Reference axis	+ 90°-axis
X, Y	+ X	+ Y
Y, Z	+ Y	+ Z
Z, X	+ Z	+ X



Tool Definition

15 TOOL DEF 28

L+12.5

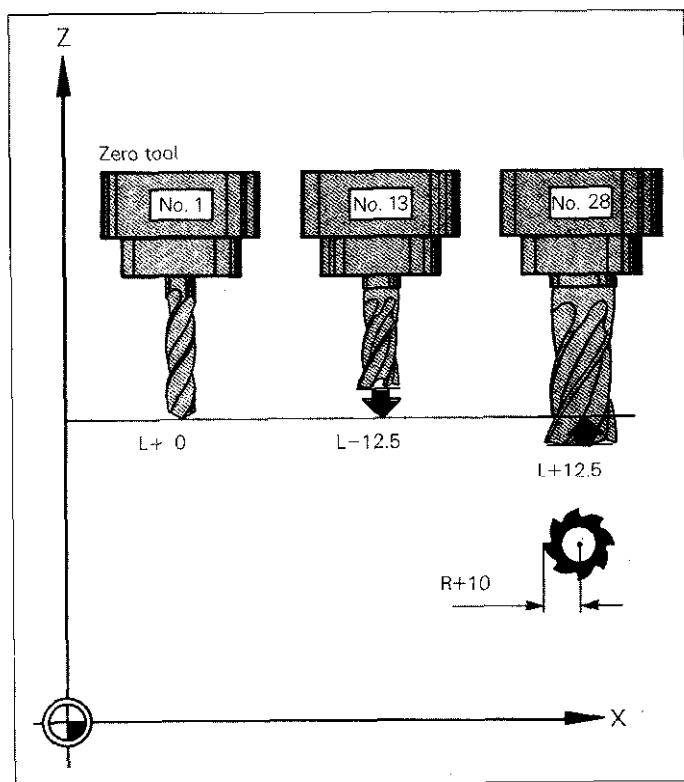
R+10

Tool length compensation:

Compensation values are referenced to the "zero tool".

Tools longer than the zero tool:
- sign

Tools shorter than the zero tool:
- sign



Tool Call

**TOOL
CALL**

```

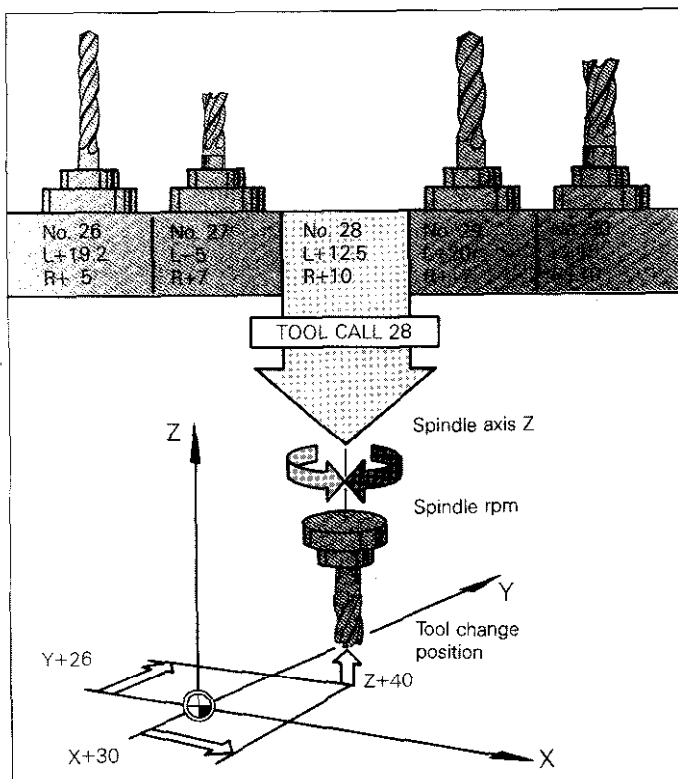
16 TOOL CALL 0          Z
17 L  X+30              Y+26
    Z+40                R0
18 STOP
                                M05
19 TOOL CALL 28          Z
    S 125
    
```

Cancellation of
current tool com-
pensation values

Tool change
position.

Program run STOP
(for manual tool
change)

Call-up of next tool
with appropriate
compensation
values.



When traversing to
the tool change
position, take care
that the tool does
not collide with the
workpiece!

The rotating direc-
tion of the spindle
is determined by a
miscellaneous func-
tion:
M03/M04 or
M13/M14
(right/left).



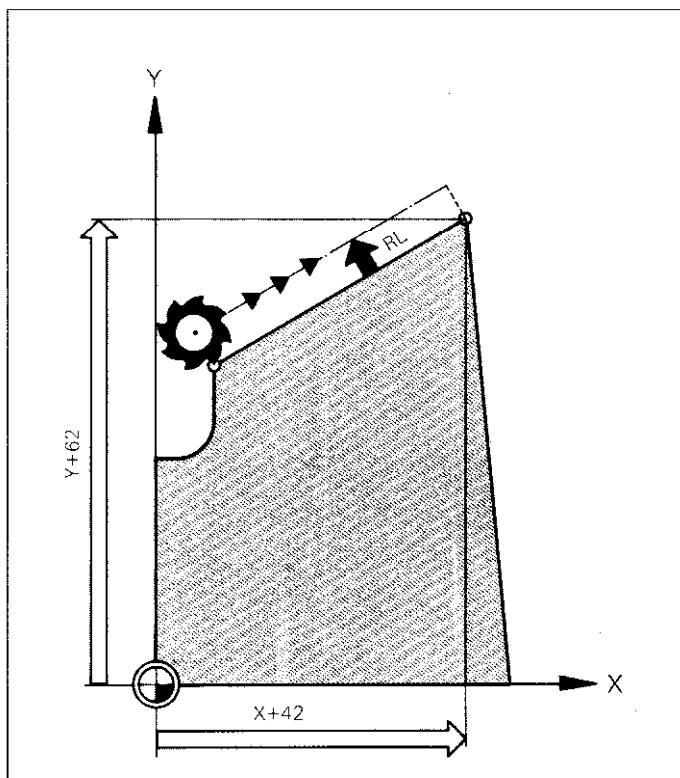
Linear Milling

Cartesian (right-angled) coordinates

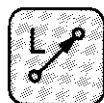
49 L X+42

Y+62

RL F180

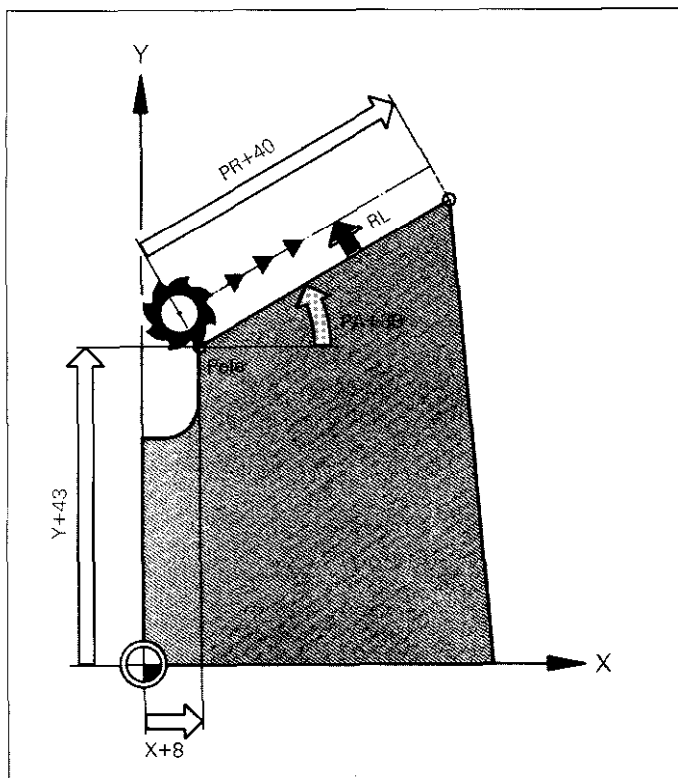


Linear Milling



Polar coordinates

```
57 CC X+8          Y+43
58 LP PR+40        PA+30
                    RL
```



Before entry of polar coordinates, define pole via the CC-key.

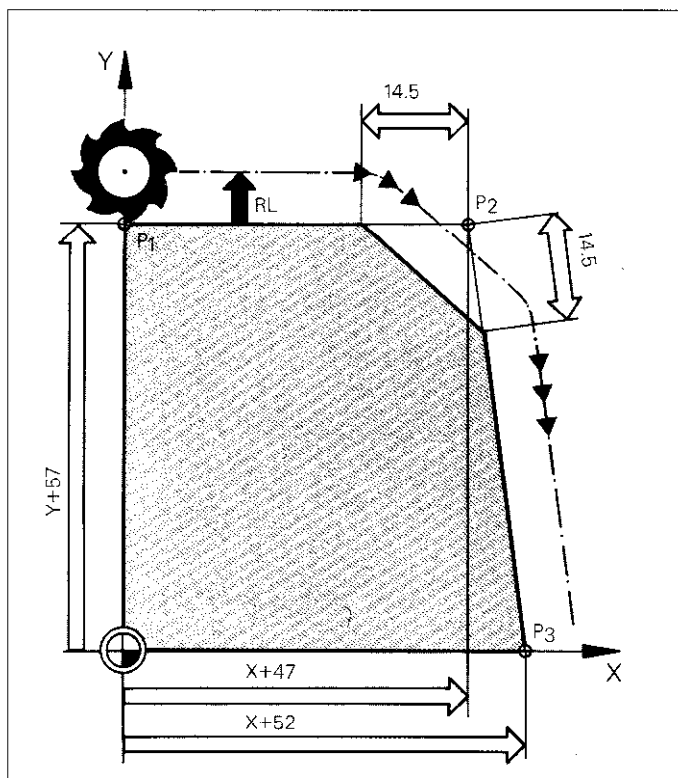
The pole must be programmed in Cartesian coordinates only!

If the pole remains the same for several blocks, a new entry is not required.



Chamfer

Auxiliary position P2	95	L	X+47	Y+57
				RL F180
Chamfer side length L	96	L	14.5	
Contour position P3	97	L	X+52	Y+0



Notes





Circular Interpolation

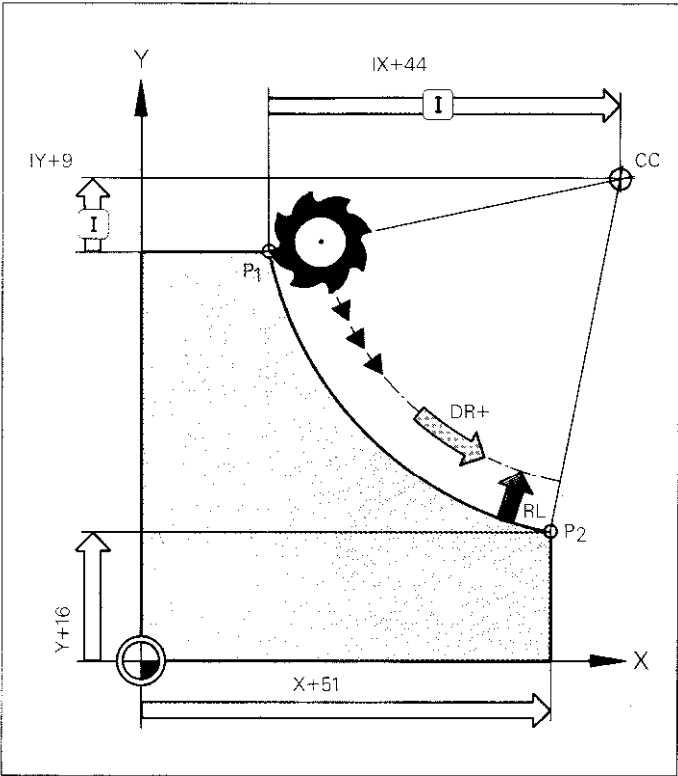
Specification via center and end position
End position in Cartesian (right-angled) coordinates

Circle center	5	CC	IX+44	IY+9
Contour position P2	6	C	X+51	Y+16
			DR+	RL F120

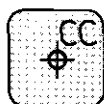
Contour position P1 (X16/Y51) has been previously approached.



- CC in absolute dimension is referenced to the program zero point.
- CC in incremental dimension is referenced to the previous contour position.



Circular Interpolation

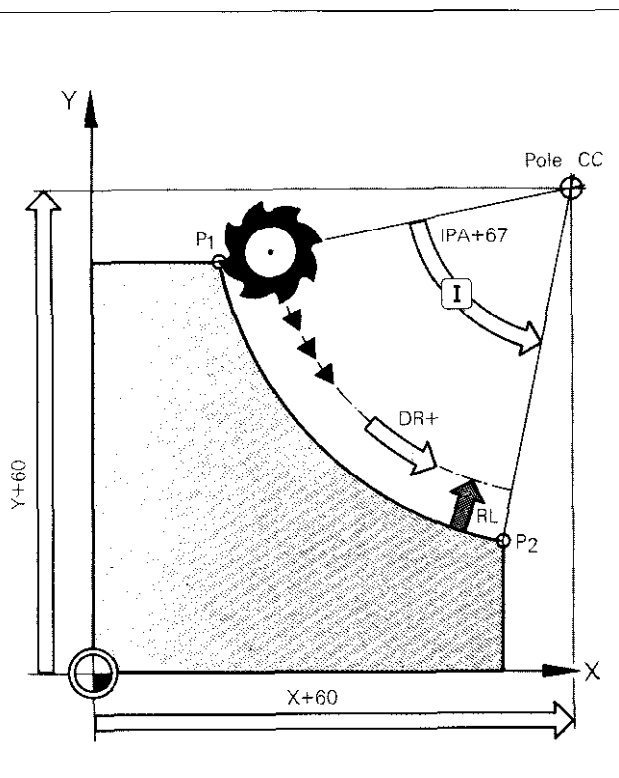


Specification via center and end position
End position in polar coordinates



5 CC X+60 Y+60
6 CP IPA+67
DR+ RL F120 M

Circle center/pole
Contour position P2



Before entry of polar coordinates, define pole via the CC-key.

The pole must be programmed in Cartesian coordinates only!

Determination of the arc end position only with polar coordinate angle PA.



Circular Interpolation

Specification via radius and end position

Contour position P2

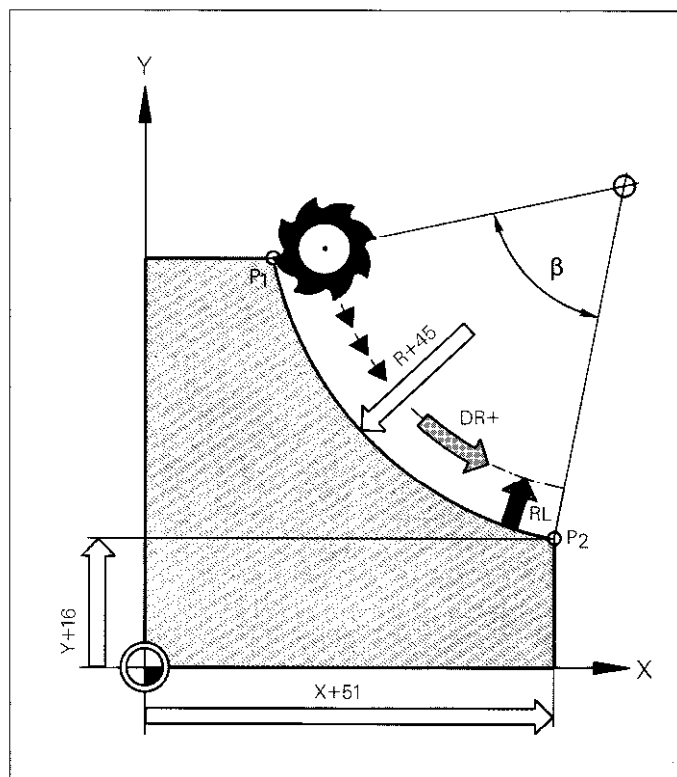
6 CR X+51
R+45

Y+16
DR+ RL F120

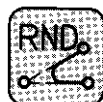
Circle radius Sign R:

Center angle β
less than 180° : R+,

Center angle β
greater than 180° :
R-.



Rounding of Corners



```

39 L X+47          Y+49
    RL F120

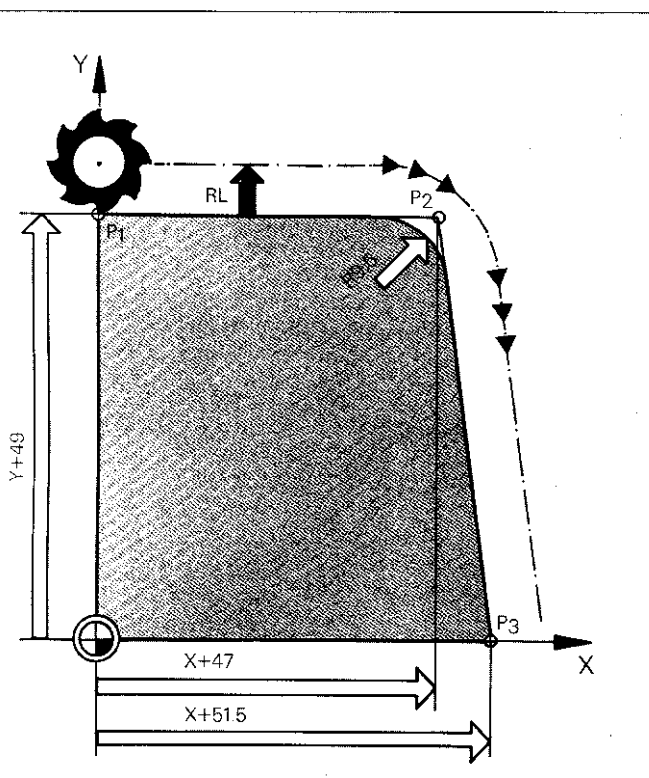
40 RND R9.5

41 L X+51.5        F80
                   Y+0
                   F120
    
```

Auxiliary position P₂

Rounding off radius R

Contour position P₃



Before and after an RND block a positioning block containing both coordinates of the machining plane must be programmed.



Circular Interpolation

Tangential contour connection
Cartesian coordinates

End position P₂
of straight

21 L X+27

Y+52.5

End position P₃
of connecting arc

22 CT IX+31

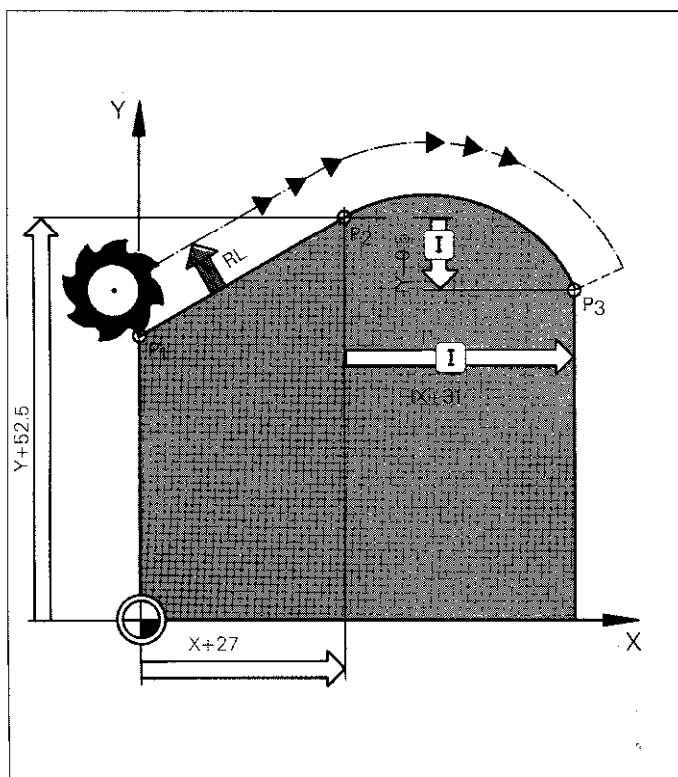
RL F100

IY-9.5

RL



A contour element
(straight or arc)
having coordinates
within the same
working plane must
already be pro-
grammed before the
connecting arc.



Circular Interpolation



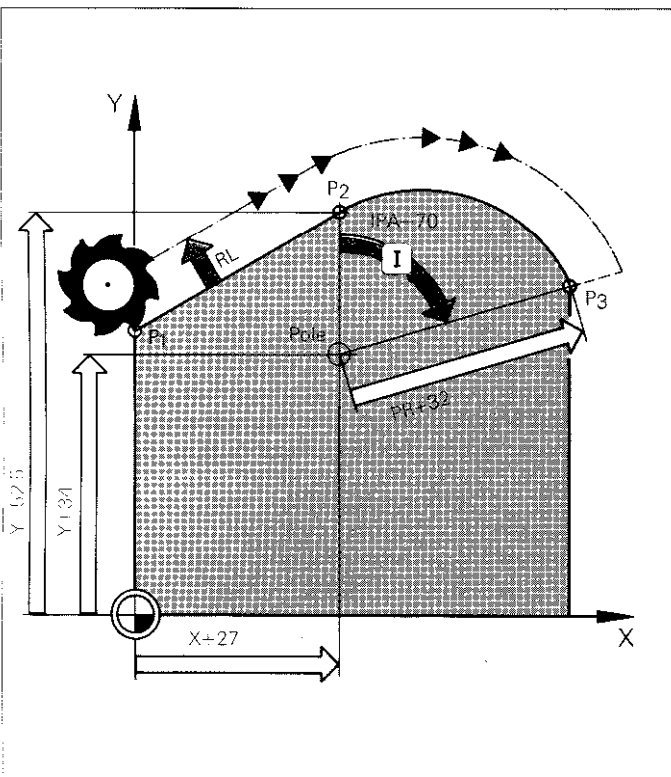
Tangential contour connection Polar coordinates

```

45 L X+27 Y+52.5
    RL F100
46 CC X+27 Y+34
47 CIP PR+32 IPA-70
    
```

End position P₂ of
straight

End position P₃ of
connecting arc



Before entry of
polar coordinates,
define pole via the
CC-key.

The pole must be
defined in Cartesian
coordinates only.

A contour element
(straight or arc)
having coordinates
within the same
working plane must
already be program-
med before the
connecting arc.



Helical Interpolation

```

64 CC X+30          Y+21
65 CP IPA-2520      IZ-12
DR- RL F80
  
```



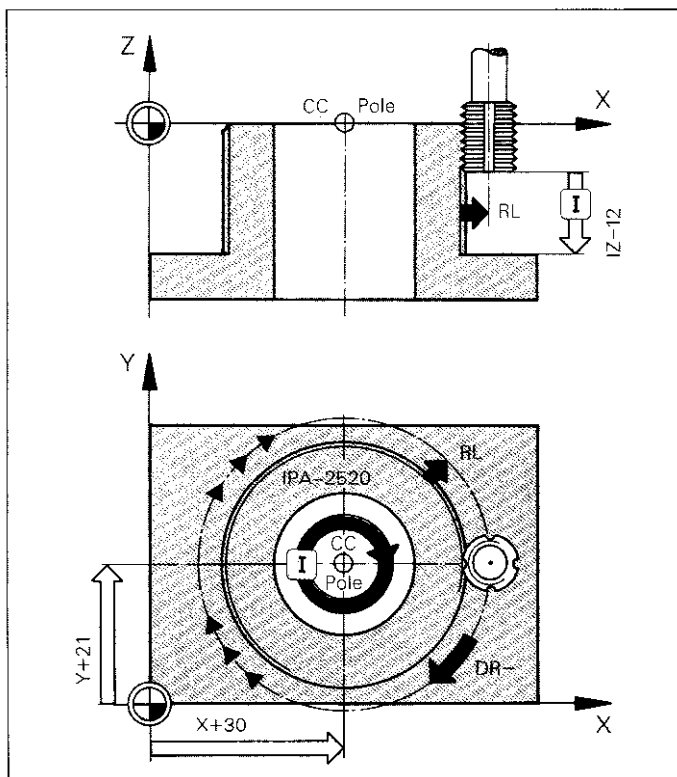
Define pole CC beforehand and approach to starting position.

Specify angle PA in incremental only!

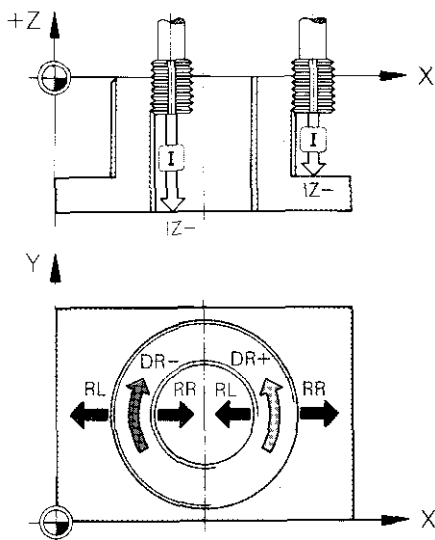
Polar coordinates angle PA is calculated as follows:

$$PA = 360 \times IZ/P$$

IZ: Downfeed distance
P: Pitch of thread



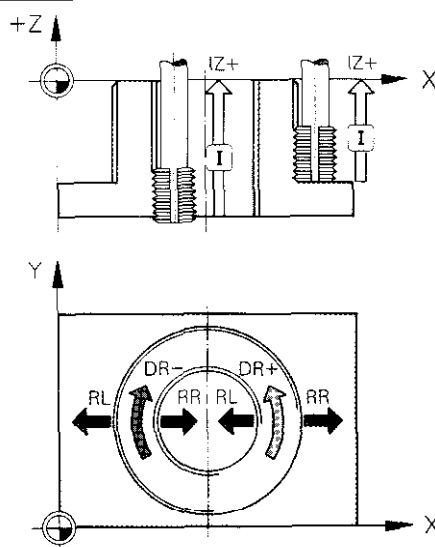
Helical Interpolation



Right-hand thread
External: down-cut
milling
Internal: up-cut
milling



Left-hand thread
External: up-cut
milling
Internal: down cut
milling



Right-hand thread
External: up-cut
milling,
Internal: down-cut
milling.



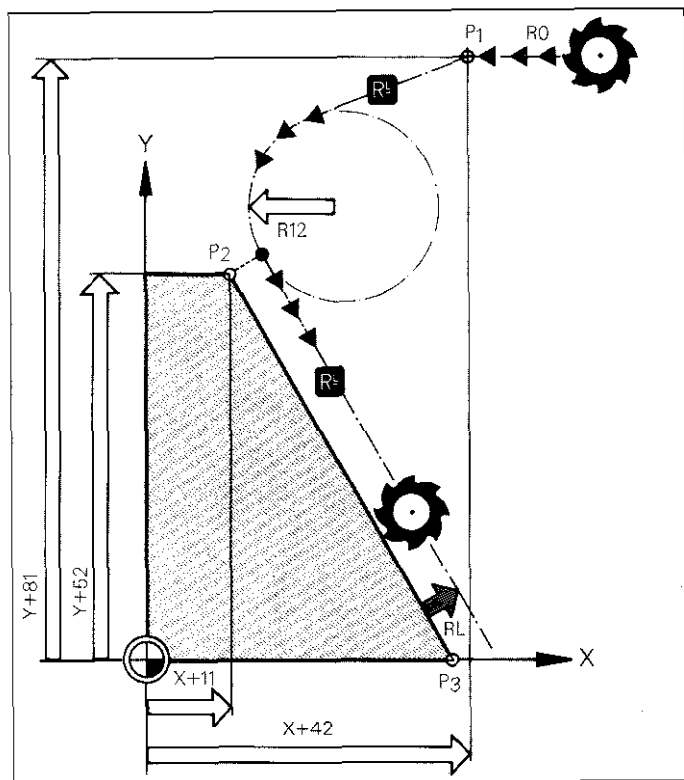
Left-hand thread
External: down-cut
milling,
Internal: up-cut
milling.

Contour Approach on an Arc

Starting position P ₁ with R0	79 L X+42	Y+81
		R0 F MAX
Contour position P ₂ with RL (RR)	80 L X+11	Y+52
		RL F80
Rounding off radius	81 RND R12	



Before and after
an RND block a
positioning block
containing both
coordinates of
the machining
plane must be pro-
grammed.



Contour Departure on an Arc

89 L X+36

Y+18
RL F80

Contour position P3
with RL (RR)

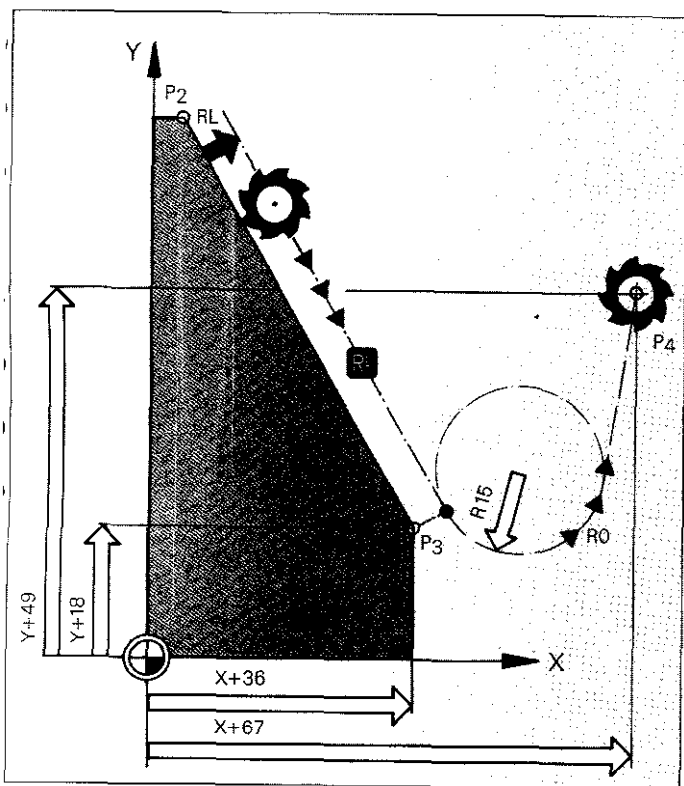
90 RND R15

Rounding off radius

91 L X+67

Y+49
R0

End position P4
with R0



Before and after
an RND block a
positioning block
containing both
coordinates of
the machining
plane must be pro-
grammed.

Contour Approach and Departure on a Straight Path

Path angle $\alpha = 180^\circ$

Starting position
P₁ with RL (RR)

28 L X+11

Y+72

RL F MAX

Contour position
P₂ with RL (RR)

29 L X+26

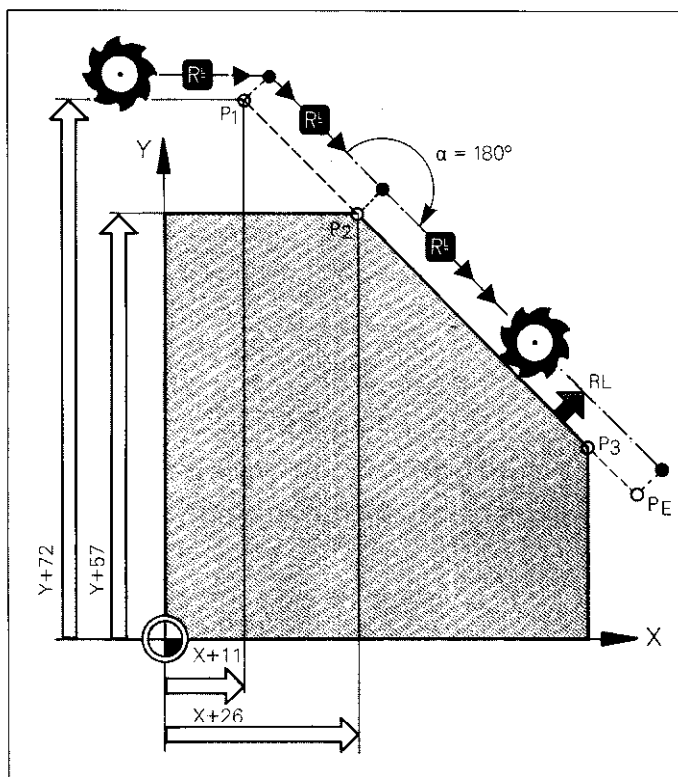
Y+57

RL F120

Program structure
for contour
departure:

Last contour posi-
tion with RL (RR),

Finishing position
P_E with RL (RR).



Contour Approach and Departure on a Straight Path

Path angle α greater than 180°

12 L X+16

Y+50

RL F MAX

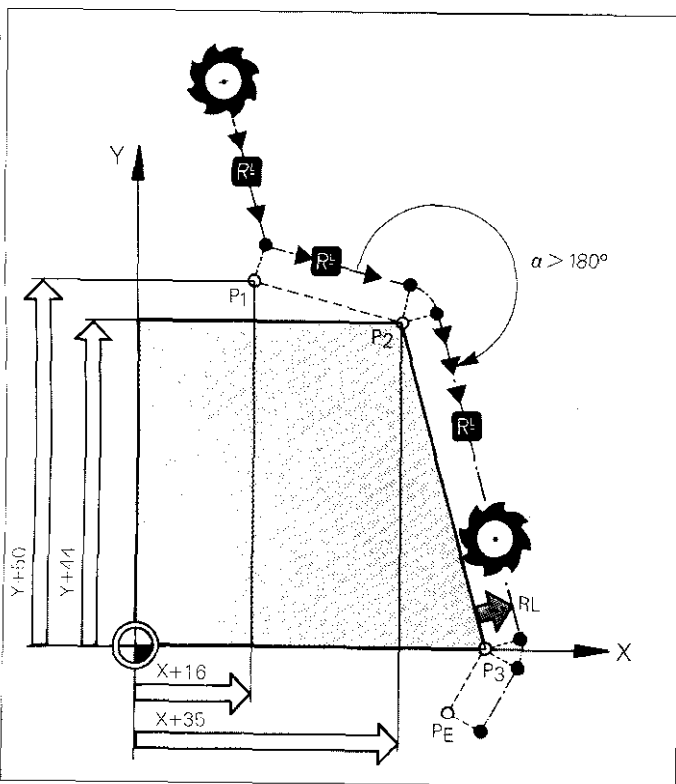
Starting position
P₁ with RL (RR)

13 L X+35

Y+44

RL F'80

Contour position
P₂ with RL (RR)



Program structure
for contour
departure:

Last contour position with RL (RR),

Finishing position P_E
with RL (RR).

Contour Approach and Departure on a Straight Path

Path angle α less than 180°

Starting position
P₁ with RL (RR)

75 L X+59

Y+72

Contour position
P₂ with RL (RR)

76 L X+27

R0 F MAX M

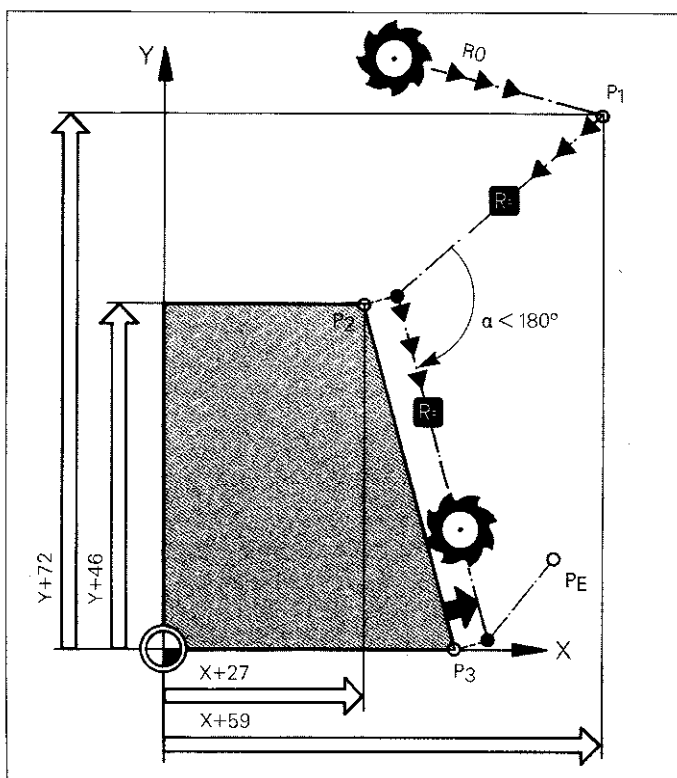
Y+46

RL F120 M

Program structure
for contour
departure:

Last contour posi-
tion with RL (RR),

Finishing position P_E
with R0.

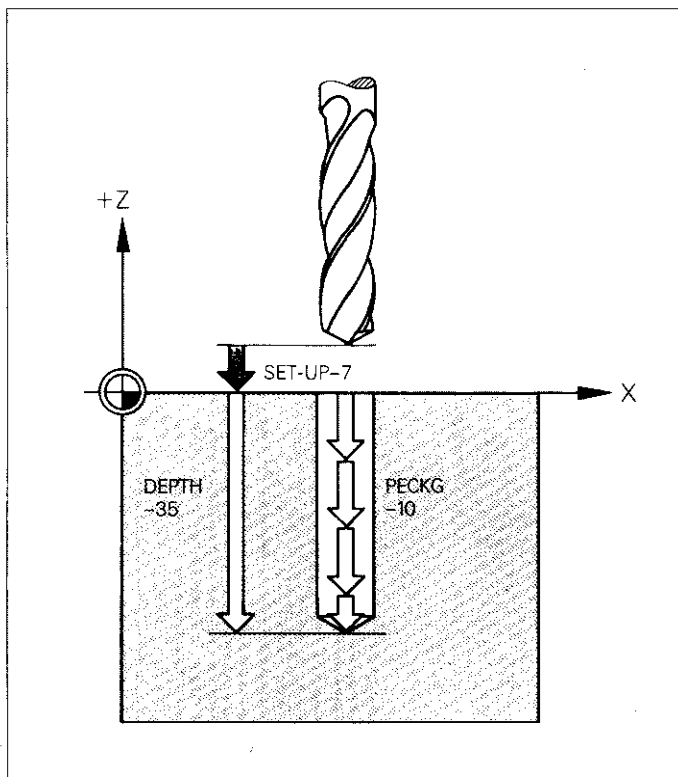


Notes



Peck Drilling

```
12 CYCL DEF 1.0 PECKING
13 CYCL DEF 1.1 SET-UP -7
14 CYCL DEF 1.2 DEPTH -35
15 CYCL DEF 1.3 PECKG -10
16 CYCL DEF 1.4 DWELL 1
17 CYCL DEF 1.5 F180
```

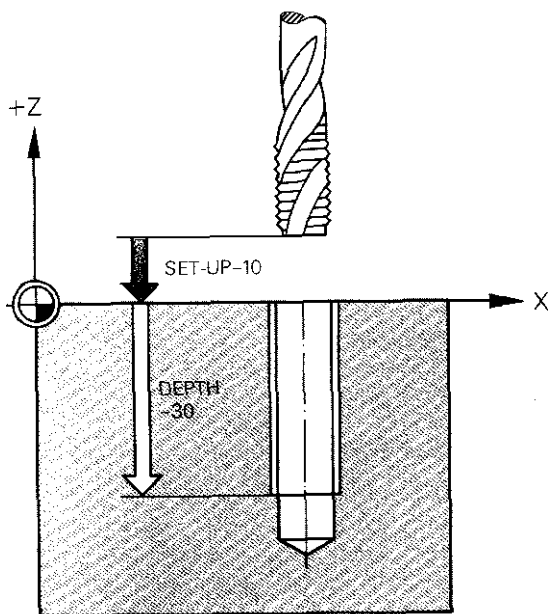


Algebraic signs of cycle parameters are entered in accordance with the direction of tool movement.

Tapping

CYCL
DEF

```
55 CYCL DEF 2.0 TAPPING
56 CYCL DEF 2.1 SET-UP -10
57 CYCL DEF 2.2 DEPTH -30
58 CYCL DEF 2.3 DWELL 1
59 CYCL DEF 2.4 F100
```



A floating tap holder is recommended for the tapping cycle.

Algebraic signs of cycle parameters are entered in accordance with the direction of tool movement.

Feed rate calculation F:
 $F = S \times P$

S: Spindle rpm,
P: Thread pitch.

Rigid Tapping

```

22 CYCL DEF 17.0 RIGID TAPPING
23 CYCL DEF 17.1 SET-UP -8
24 CYCL DEF 17.2 DEPTH -35
25 CYCL DEF 17.3 PITCH +4
  
```

The rigid tapping cycle enables you to tap **without** using a floating tap holder.

Algebraic signs of the SETUP and DEPTH parameters are entered in accordance with the direction of tool movement.

The sign for the PITCH parameter determines the thread direction:

Thread pitch: +

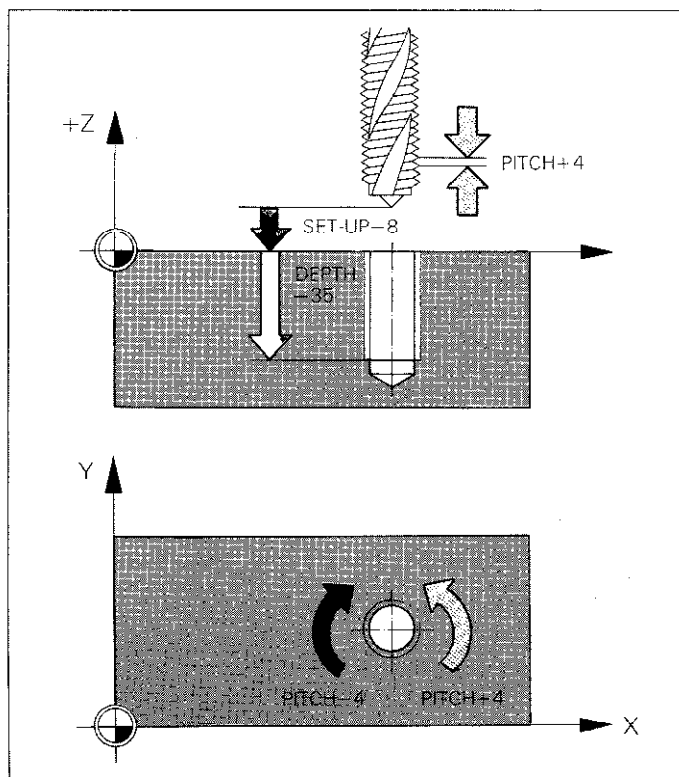


Right-hand thread,

Thread pitch: -



Left-hand thread.



Slot Milling

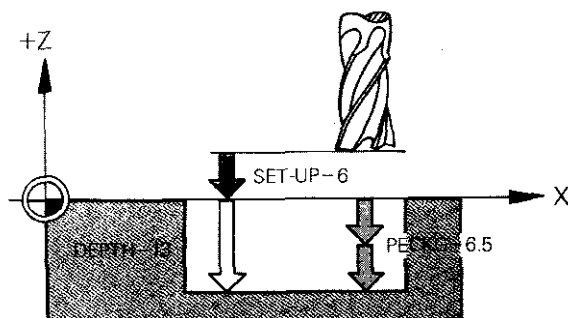
CYCL
DEF

```

14 CYCL DEF 3.0 SLOT MILLING
15 CYCL DEF 3.1 SET-UP -6
16 CYCL DEF 3.2 DEPTH -13
17 CYCL DEF 3.3 PECKKG -6.5
    F60
18 CYCL DEF 3.4 X-30.5
19 CYCL DEF 3.5 Y+10.5
20 CYCL DEF 3.6 F180
    
```

Slot length

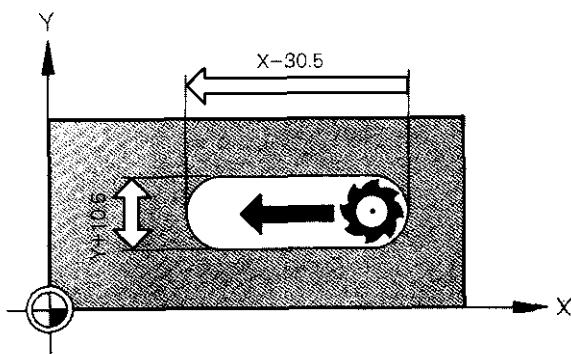
Slot width



Algebraic signs of cycle parameters are entered in accordance with the direction of tool movement.

The sign for the first side length depends on the direction of tool movement:
Positive axis direction: +,
Negative axis direction: -.

The sign for the second side length is always positive.



Rectangular Pocket Milling

```

45 CYCL DEF 4.0 POCKET MILLING
46 CYCL DEF 4.1 SET-UP -6
47 CYCL DEF 4.2 DEPTH -13
48 CYCL DEF 4.3 PECKG -6.5
   F40
49 CYCL DEF 4.4 X+31
50 CYCL DEF 4.5 Y+26
51 CYCL DEF 4.6 F140 DR+
  
```

First side length

Second side length

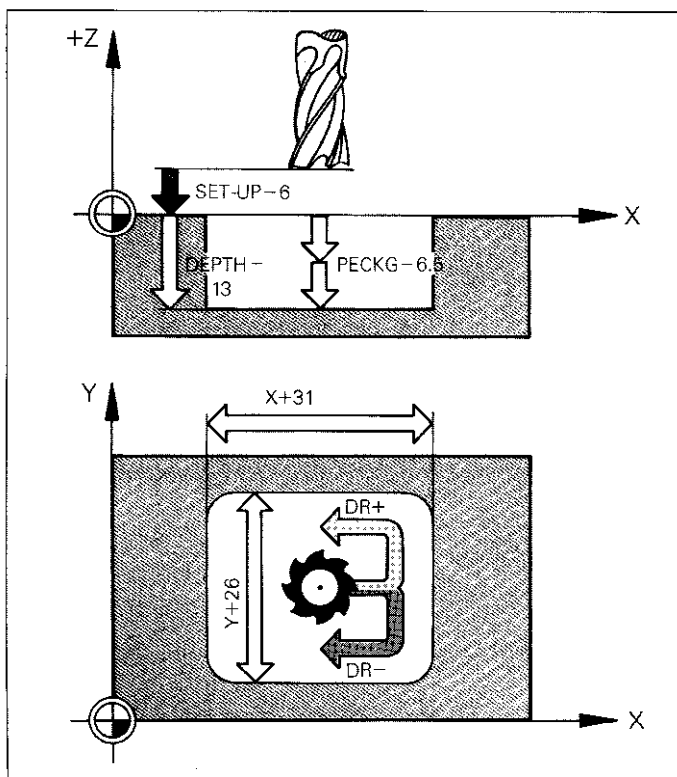
Algebraic signs of cycle parameters are entered in accordance with the direction of tool movement.

Signs for both side lengths are always positive.

DR+: down-cut milling,

DR-: up-cut milling.

Starting direction: positive axis direction of longer side.

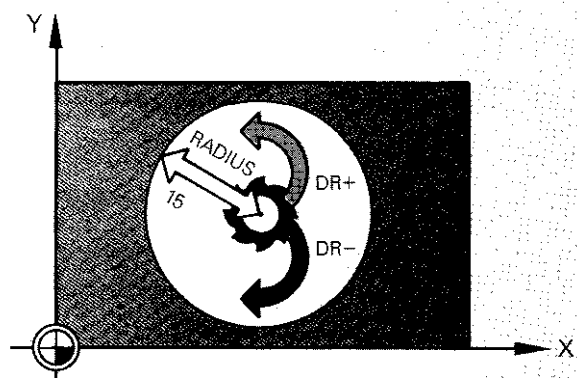
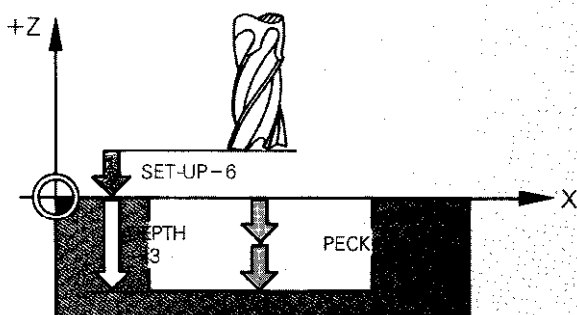


Circular Pocket Milling

CYCL
DEF

```

44 CYCL DEF 5.0 CIRCULAR POCKET
45 CYCL DEF 5.1 SET-UP -6
46 CYCL DEF 5.2 DEPTH -13
47 CYCL DEF 5.3 PECKG -6.5
   F60
48 CYCL DEF 5.4 RADIUS 15
49 CYCL DEF 5.5 F120 DR-
    
```



Algebraic signs of cycle parameters are entered in accordance with the direction of tool movement.

DR+: down-cut milling,

DR-: up-cut milling.

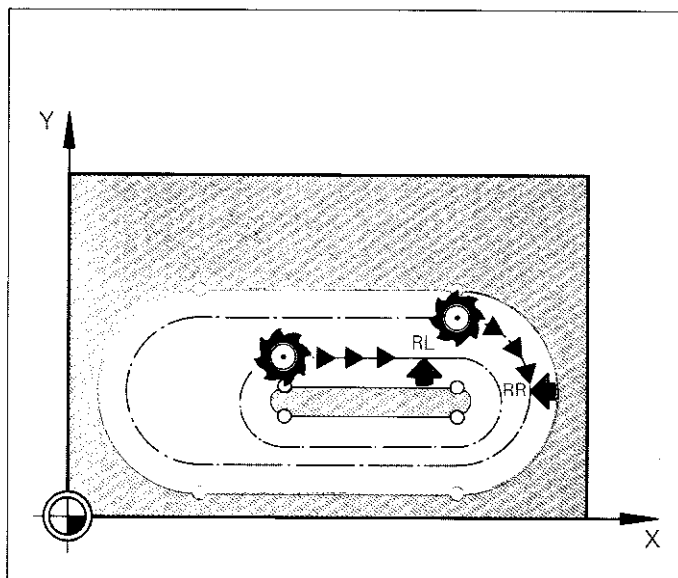
Contour Pocket Milling (SL Cycles)

Contour definition: pocket and island

Programming of
contour positions in
clockwise direction:

Pocket
Radius
compensation RR,

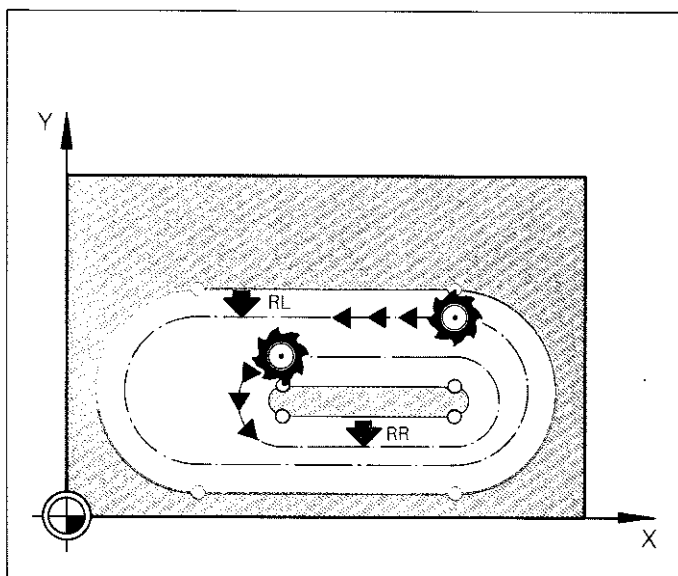
Island
Radius
compensation RL.



Programming of
contour positions in
counter-clockwise
direction:

Pocket
Radius
compensation RL,

Island
Radius
compensation RR.



Contour Pocket Milling (SL Cycles)

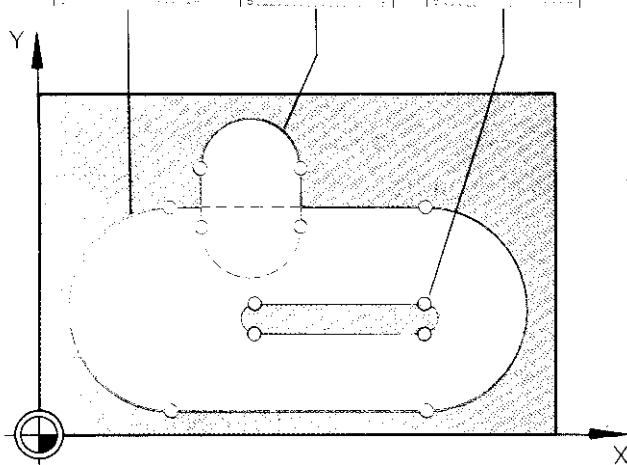
CYCL
DEF

Determination of subcontours

```
18 CYCL DEF 14.0 CONTOUR
19 CYCL DEF 14.1 CONTOUR LABEL
11 /12 /13
```

Label number of
subcontours

LBL 11	LBL 12	LBL 13
I	I	I
CC....	CC....	CC....
C	C	C
CR....	CR....	CR....
LBL 0	LBL 0	LBL 0



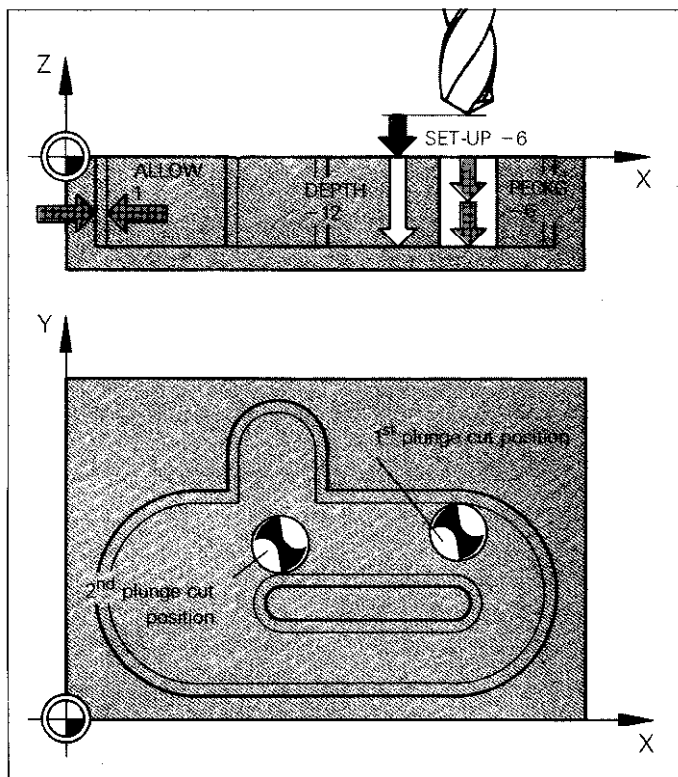
A pocket must be
programmed in the
first contour label.

Contour Pocket Milling (SL Cycles)

Pilot drill

```

23 CYCL DEF 15.0 PILOT DRILL
24 CYCL DEF 15.1 SET-UP -6
    DEPTH -12
25 CYCL DEF 15.2 PECKG -6
    F40    ALLOW+1
  
```



Algebraic signs of cycle parameters are entered in accordance with the direction of tool movement.

Plunge cuts:
First contour positions programmed in the subprograms.

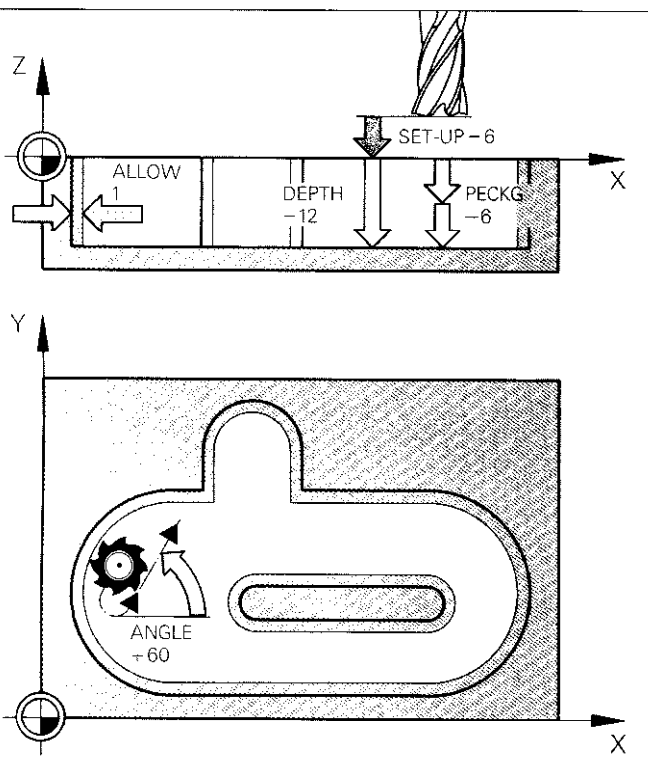
Contour Pocket Milling (SL Cycles)

CYCL
DEF

Rough-out

```

34 CYCL DEF 6.0 ROUGH-OUT
35 CYCL DEF 6.1 SET-UP -6
    DEPTH -12
36 CYCL DEF 6.2 PECKG -6
    F40        ALLOW+1
37 CYCL DEF 6.3 ANGLE +60
    F120
    
```



Algebraic signs of cycle parameters are entered in accordance with the direction of tool movement.

Starting positions: plunge cuts of pilot drill cycle.

Contour Pocket Milling (SL Cycles)

Contour milling (finish cut)

```

44 CYCL DEF 16.0 CONTOUR MILLING
45 CYCL DEF 16.1 SET-UP -6
      DEPTH -12
46 CYCL DEF 16.2 PECKG -6
      F60      DR-  F120
  
```

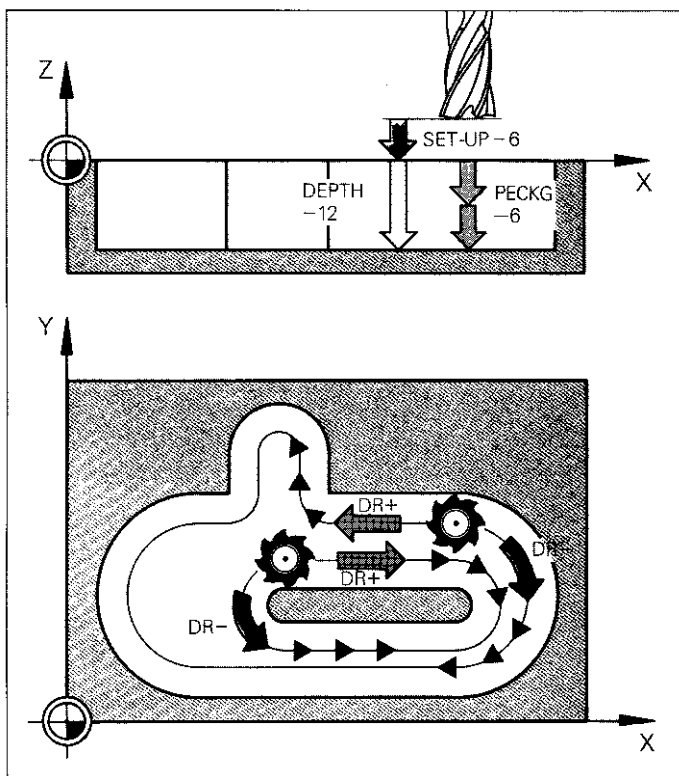
1st feed rate:
Pecking depth
2nd feed rate:
Contour milling

Algebraic signs of
cycle parameters
are entered in
accordance with
the direction of
tool movement.

DR+: down-cut
milling pocket
and island,

DR-: up-cut
milling pocket
and island.

Starting positions:
plunge cuts of pilot
drill cycle.

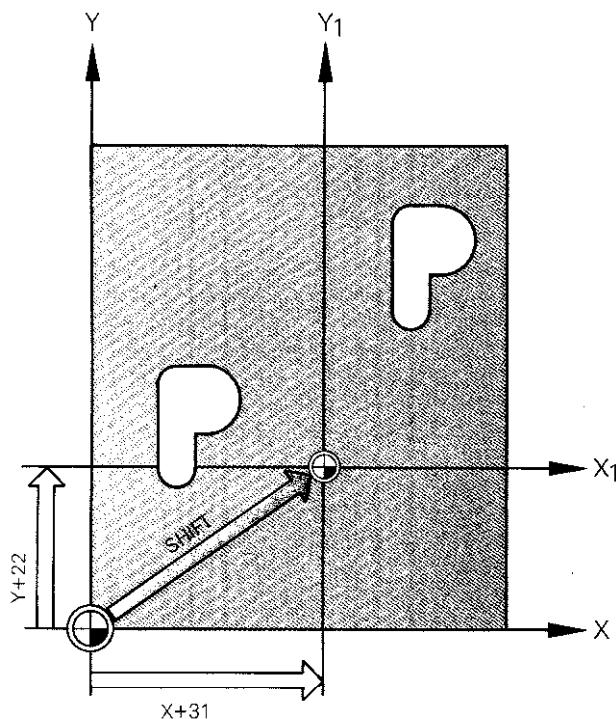


Datum Shift

CYCL
DEF

```
14 CYCL DEF 7.0 DATUM SHIFT
15 CYCL DEF 7.1 X+31
16 CYCL DEF 7.2 Y+22
```

Coordinate specification referenced to the absolute zero datum



Datum shift is possible in all 4 axes.

Coordinate specification
Absolute:
referenced to the absolute zero datum,

Incremental:
referenced to the last datum set.

Cancellation of cycle:
CYCL DEF 7 with
X0/Y0
Z0/IV0

or M02 or M30
or END PGM.

Mirror Image


Sign change of X-
coordinates

```
23 CYCL DEF 8.0 MIRROR IMAGE  
24 CYCL DEF 8.1 X
```

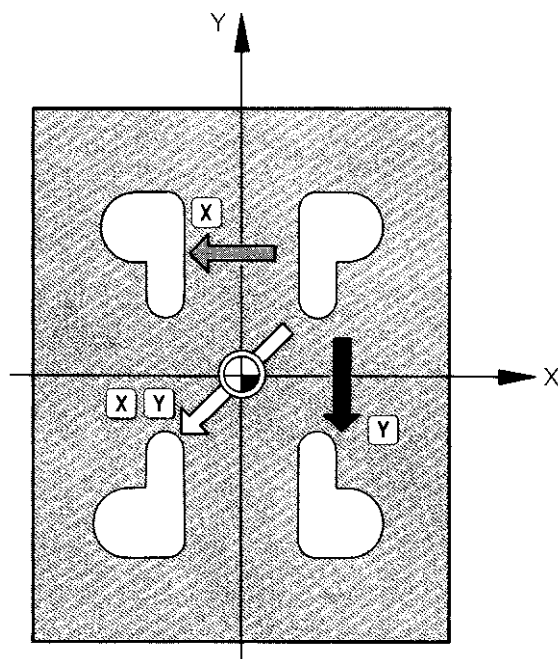
In the working
plane, mirror image
is possible on max.
2 axes.

Cancellation of cycle:

CYCL DEF 8

Respond to mirror
image with 

or M02 or M30
or END PGM.

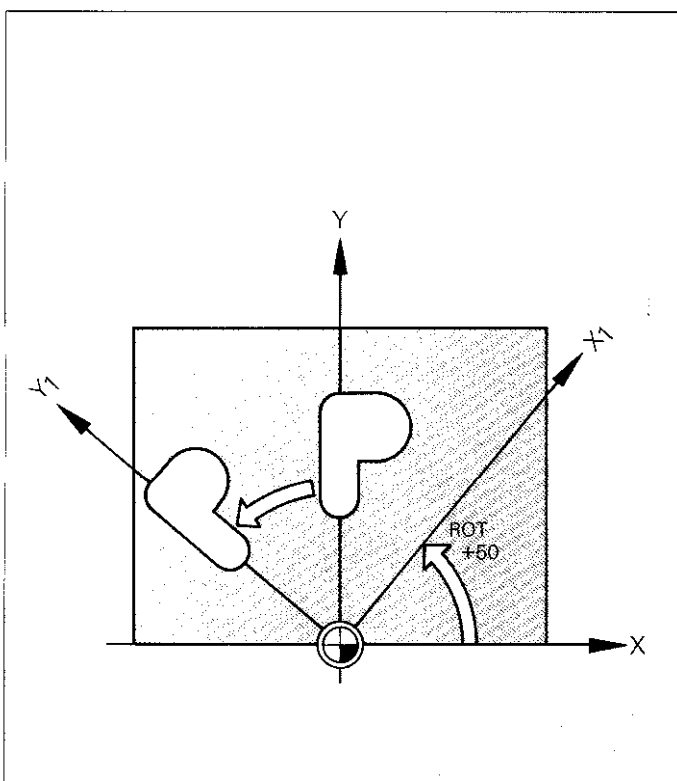


Coordinate System Rotation

CYCL
DEF

```
78 CYCL DEF 10.0 ROTATION
79 CYCL DEF 10.1 ROT+50
```

Rotation angle



Coordinate system rotation takes place in the working plane.

Cancellation of cycle:

CYCL DEF 10 with ROT 0

or M02 or M30
or END PGM.

Scaling

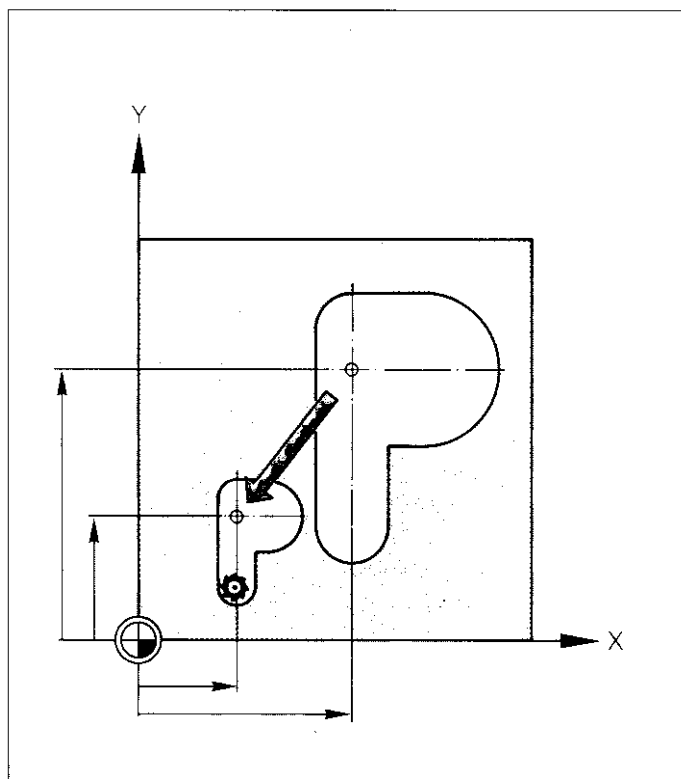
```
98 CYCL DEF 11.0 SCALING  
99 CYCL DEF 11.1 SCL 0.5
```

With the scaling factor SCL, all subsequent coordinates and radii within the working plane or the three axes X, Y and Z are multiplied by the scaling factor. Angle values remain the same.

Cancellation of cycle:

CYCL DEF 11 with
SCL 1.0

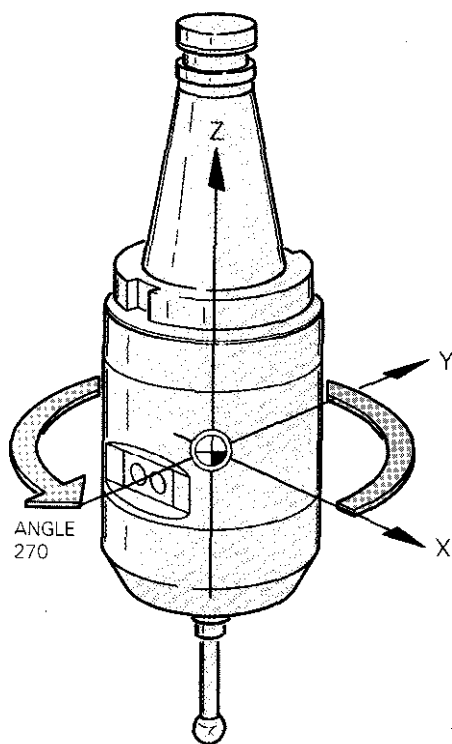
or M02 or M30
or END PGM.



Oriented Spindle Stop

CYCL
DEF

38 CYCL DEF 13.0 ORIENTATION
39 CYCL DEF 13.1 ANGLE 270



The cycle is called with an M function determined by the machine tool builder.

LBL
SET

Subprograms

LBL
CALL

Subprogram call

Call subprogram

```
42 CALL LBL 7      REP
```

•

Return jump to first
program block

```
55 M30
```

•

Beginning of
subprogram

```
70 LBL7
```

•

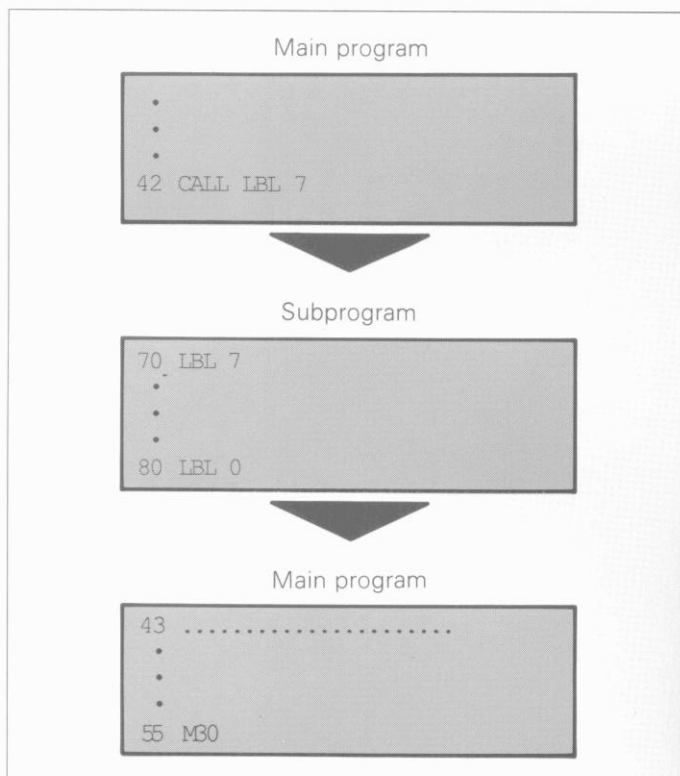
End of subprogram

```
80 LBL 0
```

Main program and
subprogram form
parts of a complete
program.



With a subprogram
call, repetitions
(REP) must not be
programmed.



Program Section Repeat

LBL
SET

LBL
CALL

```
28 LBL 51
```

•

```
39 CALL LBL 51    REP 3/3
```

Beginning of
program section

Program section
end is also a call-up
for repetition

```
28 LBL 51
```

•
•
•

```
39 CALL LBL 51    REP 3/3
```

```
28 LBL 51
```

•
•
•

```
39 CALL LBL 51    REP 3/2
```

```
39 CALL LBL 51    REP 3/1
```

```
39 CALL LBL 51    REP 3/0
```

```
40 .....  
•  
•  
•
```

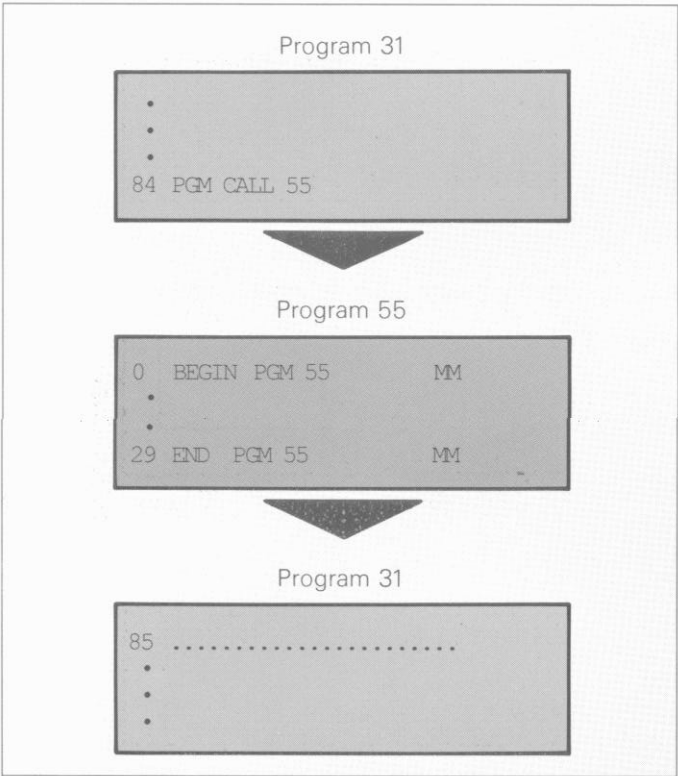
REP 3/3:

The countdown numeral after the stroke indicates the number of repetitions still to be executed. It decreases by 1 on completion of each repetition.

84 PGM CALL 55

In block 84 of program No. 31 a jump is made to the beginning of program No. 55.

At the end of program No. 55 a return jump is made to program No. 31 continuing from block 85.



Program Call Cycle

CYCL
DEF

```
18 CYCL DEF 12.0 PGM CALL
```

```
19 CYCL DEF 12.1 PGM 55
```

•

```
22 CYCL CALL
```

Call-up of CYCL 12

Program 31

```
18 CYCL DEF 12.0 PGM CALL
```

```
19 CYCL DEF 12.1 PGM 55
```

•

```
22 CYCL CALL
```



Program 55

```
0 BEGIN PGM 55 MM
```

•

•

```
29 END PGM 55 MM
```



Program 31

```
23 .....  
•  
•  
•
```

At block 22 of program No. 31 a jump is made to the beginning of program No. 55.

At the end of program No. 55 a return jump is made to program No. 31 continuing from block 23.

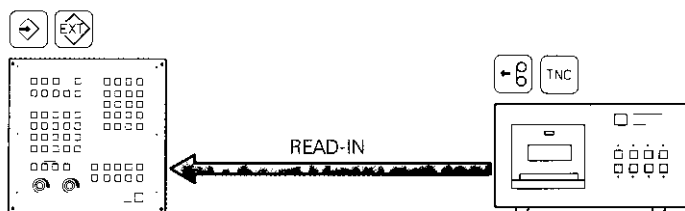
Cycle call can be initiated with either CYCL CALL or M99 or M89.

External Data Transmission

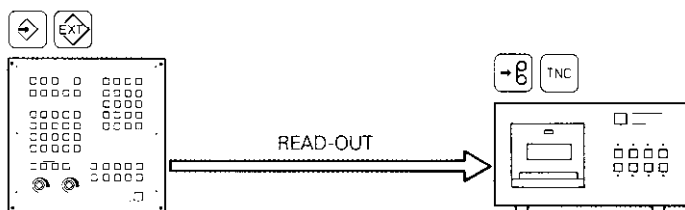
V.24/RS-232-C data interface of TNC Interface modes

V.24/RS-232-C INTERFACE = ME

Transfer rate: 2400 baud

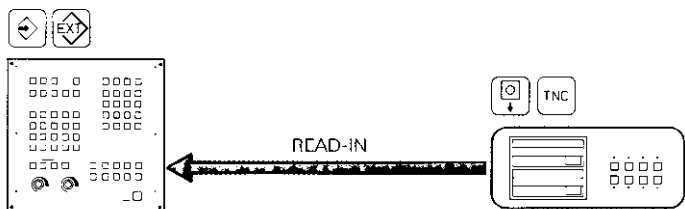


Operation of the
magnetic tape unit
is only possible in
the interface mode
ME.

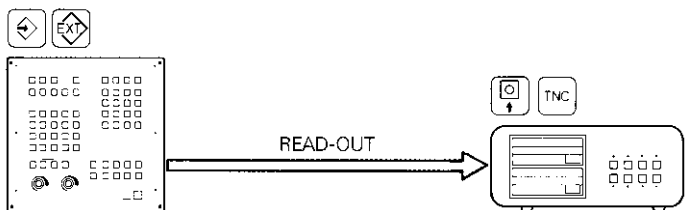


V.24/RS-232-C INTERFACE = ME

Transfer rate: 2400 baud



Operation of the
disk unit is only
possible in the inter-
face modes ME and
FE.

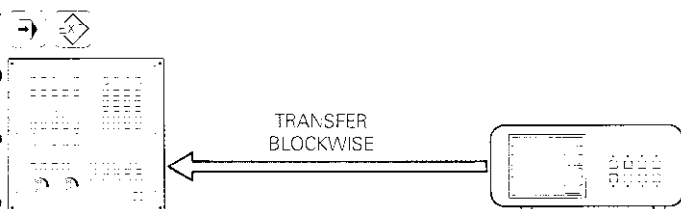
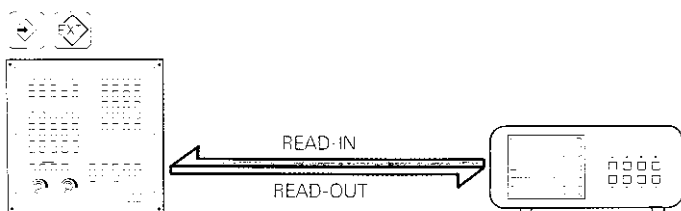


External Data Transmission

V.24/RS-232-C data interface of TNC Interface modes

V.24/RS-232-C INTERFACE = FE

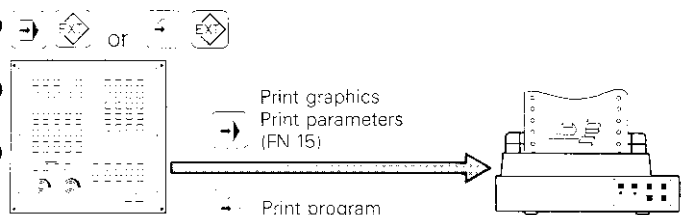
Transfer rate: 38400 baud



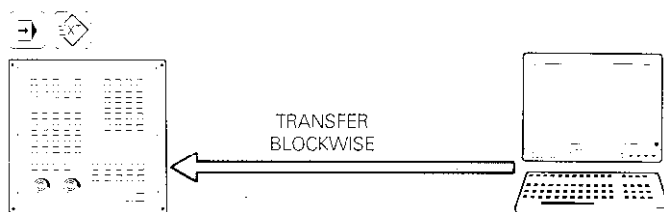
In FE mode,
operation of disk
unit only via TNC
keyboard.

V.24/RS-232-C INTERFACE = EXT

Transfer rate: 38400 baud
other baud rates programmable



Please observe the
notes in the TNC
interface descrip-
tion with the
EXT-operation.



Spindle axis Z and
Point P_{min}

Point P_{max}

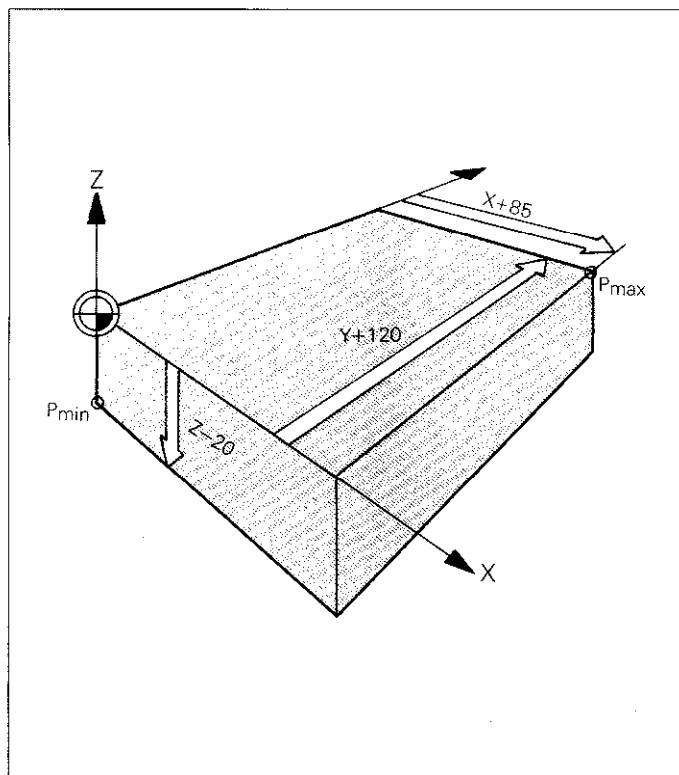
1	BLK	FORM	0.1	Z	X+0	
					Y+0	Z-20
2	BLK	FORM	0.2		X+85	
					Y+120	Z+0

BLK FORM:
Blank form
= shape of blank

The working plane
is always perpendicular
to the spindle
axis.

P_{min}: Only in
absolute
dimensions

P_{max}: Either
absolute or
incremental
dimensions



Manual shift of sectional plane _____

In opposite direction _____

Automatic shift of sectional plane _____

In opposite direction _____

Shift stop _____

Select next sectional plane (forward paging) _____

Select previous sectional plane (reverse paging) _____

TRANSFER GRAPHICS DETAIL = ENT

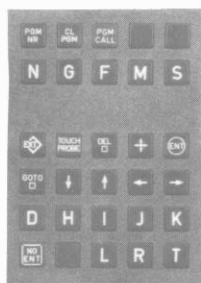
Start program run _____



Before selecting the magnify function, the control must be in the graphics mode "3D-view".

Programming in ISO Format

Letter Addresses



%	Program beginning or program call	P	Cycle parameter for
%	Program call with G39	P	fixed cycles
A	Rotary axis about X-axis		Parameter in parameter
B	Rotary axis about Y-axis		definition
C	Rotary axis about Z-axis	Q	Q-parameter
D	Parameter definition (Parameter Q)	R	Radius for polar coordinates
F	Feed code	R	Circle radius with G02/G03/G05
F	Dwell time with G04	R	Round-off radius w. G25/G26/G27
F	Scaling factor with G72	R	Chamfer with G24
G	Preparatory "GO" function	R	Tool radius with G99
H	Angle for polar coordinates	S	Spindle speed
H	Rotational angle with G73	S	Spindle position with G36
I	X-Coordinate of circle center/pole	T	Tool definition with G99
J	Y-Coordinate of circle center/pole	T	Tool call
K	Z-Coordinate of circle center/pole	T	Next tool with G51
L	Set label number with G98	U	Additional linear axis parallel to X-axis
L	Jump to label number	V	Additional linear axis parallel to Y-axis
L	Tool length with G99	W	Additional linear axis parallel to Z-axis
M	Miscellaneous function	X	X-Axis command
N	Block number	Y	Y-Axis command
		Z	Z-Axis command
			End of block

Programming in ISO Format



Parameter Definitions

D-
code

Function

D00 Assignment

D01 Addition

D02 Subtraction

D03 Multiplication

D04 Division

D05 Root

D06 Sine

D07 Cosine

D08 Root of sum of squares

D09 if equal, jump

D10 if not equal, jump

D11 if greater, jump

D12 if less, jump

D13 Angle ($r \cdot \sin \alpha$ and $r \cdot \cos \alpha$)

D14 Error number

D15 Print (output of parameters)

Programming in ISO Format

G-Codes

G00	Linear interpolation, Cartesian, in rapid
G01	Linear interpolation, Cartesian
G02	Circular interpolation, Cartesian CW
G03	Circular interpolation, Cartesian CCW
G05	Circular interpolation, Cartesian, without direction data
G06	Circular interpolation, Cartesian, tangential
● G07	Single axis block
G10	Linear interpolation, polar, in rapid
G11	Linear interpolation, polar
G12	Circular interpolation, polar CW
G13	Circular interpolation, polar CCW
G15	Circular interpolation, polar, without direction data
G16	Circular interpolation, polar, tangential contour approach
● G04	Dwell
G28	Mirror image
G36	Oriented spindle stop
G37	Contour geometry
● G39	Designates program for call-up via G79
G54	Datum shift
G56	Pilot drill (with G37)
G57	Rough-out (with G37)
G58	Contour mill CW (with G37)
G59	Contour mill CCW (with G37)
G72	Scaling
G73	Coordinate system (plane) rotation
G74	Slot milling
G75	Rectangular pocket milling CW
G76	Rectangular pocket milling CCW
G77	Circular pocket milling CW
G78	Circular pocket milling CCW
G83	Pecking
G84	Tapping
● G79	Cycle call

Programming in ISO Format



G-Codes

G17	XY-plane designation, Tool axis Z
G18	ZX-plane designation, Tool axis Y
G19	YZ-plane designation, Tool axis X
G20	FOURTH tool axis
● G24	Chamfer with R
● G25	Rounding of corners with R
● G26	Tangential contour approach (run-on) with R
● G27	Tangential contour departure (run-off) with R
● G29	Transfer of last nominal position value as pole
G30	Blank form definition for graphics – min. point
G31	Blank form definition for graphics – max. point
● G38	Program run STOP
G40	No tool compensation (R0)
G41	Tool radius compensation to contour, offset left (RL)
G42	Tool radius compensation to contour, offset right (RR)
G43	Paraxial compensation extension (R+)
G44	Paraxial compensation reduction (R–)
G50	Erase/Edit protection (at program beginning)
● G51	Subsequent tool number (with central tool memory)
● G55	Touch probe function
G70	Dimensioning in inches (at program start)
G71	Dimensioning in millimeters (at program start)
G90	Absolute dimensioning
G91	Incremental dimensioning
● G98	Assign label number
● G99	Tool definition

● = G-codes which are effective blockwise only

Miscellaneous functions M

M-functions which affect program run
(List of standard miscellaneous functions. These may only be changed by the machine manufacturer.)

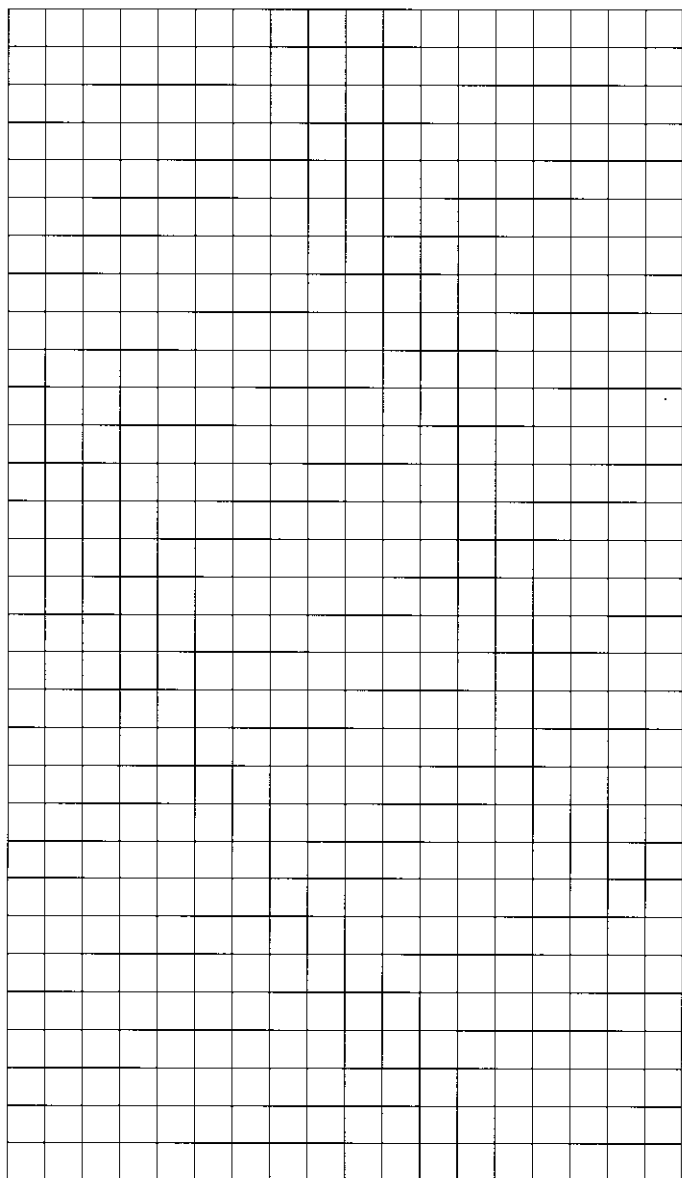
M-code	Function	Effective at	
		block begin.	block end
M00	Program run stop Spindle stop Coolant off		●
M02	Program run stop Spindle stop Coolant off Return jump to first program block		●
M03	Spindle on, clockwise	●	
M04	Spindle on, counter-clockwise	●	
M05	Spindle stop		●
M06	Tool change Program run stop (depends on machine parameters entered) Spindle stop		●
M08	Coolant on	●	
M09	Coolant off		●
M13	Spindle on, clockwise Coolant on	●	
M14	Spindle on, counter-clockwise Coolant on	●	
M30	As per M02		●

Miscellaneous functions M

M-functions which affect program run
(List of standard miscellaneous functions. These may only
be changed by the machine manufacturer.)

M-code	Function	Effective at	
		block begin.	block end
M89	Free miscellaneous function or	●	
M89	Cycle call, modally effective (depending on the machine parameters entered)		●
M90	Constant path feed rate on external and internal corners	●	
M91	Within a positioning block: Workpiece zero datum is replaced by reference point	●	
M92	Within a positioning block: The set workpiece zero datum is replaced by a position which is defined by the machine tool builder using a machine parameter, (e.g. tool change position).	●	
M93	Reserved	●	
M94	Rotary table axis display reduction to a value below 360°	●	
M95	Reserved		●
M96	Reserved		●
M97	Compensation of path intersection on external corners: point of intersection instead of transitional arc		●
M98	End comp. of path intersection blockwise		●
M99	Cycle call blockwise		●

Notes



Operating modes

"Manual",

"Electronic handwheel",

"Positioning with MDI",

"Automatic" and

"Program run in single block".

auxiliary modes, parameter programming and single-axis machining via the axis keys are not dealt with in this PILOT.

Detailed information on these topics is provided in the Operating Manual TNC 360.



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